

# Software Testing and Validation

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Corso di Laurea in Informatica

## The Murphi Model Checker

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- Murphi or  $\text{Mur}\varphi$ , the simplest among “model checkers”
  - as all model checkers we will see in this course, Murphi may be freely downloaded with the source code, thus it may also be modified
  - links for download of all model checkers we will see are on the course web-page: [https://igormelatti.github.io/sw-test\\_val/20252026/index.html](https://igormelatti.github.io/sw-test_val/20252026/index.html)



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- Formally, as all model checkers, Murphi needs the following input:
  - ➊ a description of the system  $\mathcal{S}$  you want to verify (i.e., the “model” you want to “check”)
    - as we will see, this is essentially a Kripke structure
  - ➋ a property  $\varphi$  you want the system  $\mathcal{S}$  to satisfy
- The output will be either OK or FAIL
  - if FAIL, it is possible to tell Murphi to print a *counterexample*

- In Murphi, both the description of  $\mathcal{S}$  and of  $\varphi$  must be written in a single text file, following a precise syntax
  - in other model checkers we will see (e.g., SPIN), this syntax has a name; but this is not the case for Murphi
  - thus, we will refer to it simply as *Murphi input language*
  - as we will see, in many points Murphi input language is similar to some imperative programming languages, especially Pascal (for statements) and C (for expressions)

A description for  $S$  and  $\varphi$  written in the Murphi input language must be organized as follows

- 1. definitions of:
  - *constants*, also named *parameters*
  - *data types*, divided in *simple* and *composed*
    - there are only two simple types: *enumerations* and *integer subranges*
    - the *boolean* data type is predefined as an enumeration (true, false)
    - the composed types are formed using *array* and/or *records* (structs), possibly mixed, following the Pascal syntax



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- 1. (Continuing)
  - *global variables*, each having one of the types above
    - global variables are fundamental, as they define the *states space*  $S$
    - that is,  $S$  is defined by all possible values of all global variables
    - thus, is defined by the Cartesian product of all types of all global variables defined
    - as all types are *finite*,  $S$  may be huge but it is always finite
    - see example below
  - note that such definitions may be mixed, of course keeping in mind variables scoping
    - e.g., if you need constant  $A$  to define type  $B$  of variable  $C$ , you must define constant  $A$  first, then type  $B$  and finally variable  $C$
    - type  $B$  could also be used inline directly when declaring  $C$

- 2. Definitions of:

- functions*

- return a value
    - may have side effects (i.e., modify a global variable)
    - may modify input arguments, but must be explicitly stated as in Pascal (parameter passed as *reference*)

- procedures*

- do not return a value
    - may have side effects (i.e., modify a global variable)
    - may modify input arguments, but must be explicitly stated as in Pascal (parameter passed as *reference*)

- For both functions and procedures:
  - Pascal-like syntax
  - it is possible to define and use *local* variables
  - local variables *must not* be considered in the definition of the state space  $S$
- Again, you can mix them, provided scoping is respected
- E.g., if function  $F$  calls procedure  $G$  which calls function  $H$ , then  $G$  must be defined before  $F$  and  $H$  before  $G$

- 3. Definitions (mixed as you like it) of:
  - *start states*, defined as Pascal-like statements, intended as atomically executed
    - may contain the typical statements of imperative programming languages: assignments, cycles, ifs, functions and procedures calls
    - local variables may be defined
  - *rules*, each defined by:
    - a(*n application*) *guard*, defining if a rule is applicable (*fired*, as Murphi says) or not
    - a *body*, again formed by atomically executed Pascal-like statements
    - an optional string, working as a short comment for the rule
    - by the way, comments may be either with C syntax (/\*\*/) or Pascal syntax (--)

- Of course the guard must be a boolean expression
- Only global variables and constants may occur in a guard
  - actually, also ruleset indexes, we will be back on this
- It is possible to call functions (not procedures!)
- The body may contain the typical statements of imperative programming languages: assignments, cycles, ifs, functions and procedures calls
- Local variables may be defined and used

- 3. (Continuing):
  - *invariants*, each of them defines a property to be checked
    - same as guards: it must be a boolean expression
    - only global variables and constants may occur in a guard
    - exceptions are possible when `forall` or `exist` are used
    - it is of course possible to call functions
- Finally, at least one initial state and one rule must be present (see `00.minimal.model.m`)

- Murphi checks that all reachable states of  $S$  satisfy all invariants
  - a state  $s \in S$  is *reachable* if there exists a path in the transition graph from an initial state to  $s$
  - that is: starting from an initial state, there exists a chain of rules, each applied to the state obtained from the preceding one, leading to  $s$
  - this is a *safety* property

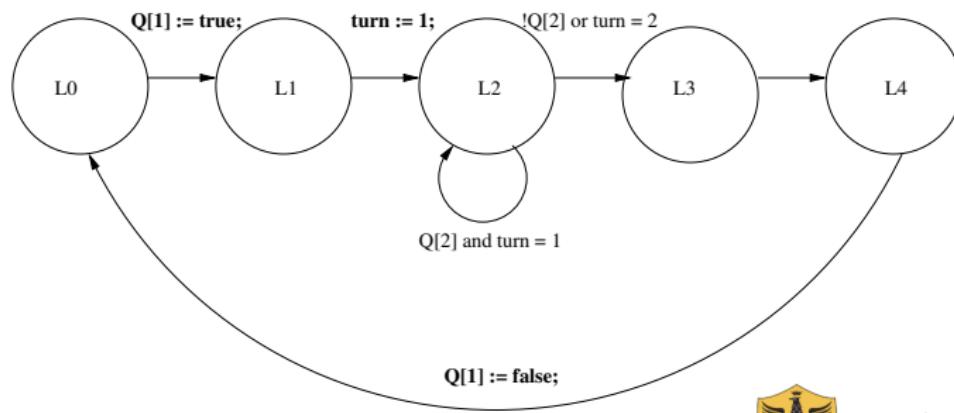
- Example: G. L. Peterson protocol for mutual exclusion of 2 processes (1981)

```
boolean flag [2];
int turn;
void P0()
{
    while (true) {
        flag [0] = true;
        turn = 1;
        while (flag [1] && turn == 1) /* do nothing */;
        /* critical section */;
        flag [0] = false;
        /* remainder */;
    }
}
void P1()
{
    while (true) {
        flag [1] = true;
        turn = 0;
        while (flag [0] && turn == 0) /* do nothing */;
        /* critical section */;
        flag [1] = false;
        /* remainder */;
    }
}
void main()
{
    flag [0] = false;
    flag [1] = false;
    parbegin (P0, P1);
}
```

### Peterson's Algorithm



- Example: G. L. Peterson protocol for mutual exclusion of 2 processes (1981)
- UML-like state diagram: this is the first process; the second may be obtained exchanging 1's with 2's and viceversa



- Example: G. L. Peterson protocol for mutual exclusion of 2 processes (1981)
  - two identical processes
  - each applies Peterson protocol to access to the critical section L3
  - the first issuing the request enters L3
  - Q is a global variable, defined as an array of two integers
    - each process  $i$  may modify  $Q[i]$  and read  $Q[(i + 1) \bmod 2]$
  - turn is another global variable, which may be both read and modified by both processes

- Murphi description for Peterson protocol: let's start with the variables
  - of course turn and Q, but also two variables P for the modality ("states" in the UML-like state diagram)
  - see 01.2.peterson.no\_rulesets.no\_parametric.m
  - to this aim, we define constants and types
  - the N constant (number of processes) is here fictitious: only 2 processes, not more
  - this version of Peterson protocol only works for 2 processes
- thus, the state space is

$$S = \text{label\_t}^2 \times \{\text{true}, \text{false}\}^2 \times \{1, 2\}$$



# Variables for Murphi Model Describing Peterson Protocol

P         $v \in \{L0, L1, L2, L3, L4\}$

$v \in \{L0, L1, L2, L3, L4\}$

Q         $v \in \{true, false\}$

$v \in \{true, false\}$

turn     $v \in \{1..N\}$



- Hence,  $|S| = 5^2 \times 2^2 \times 2 = 200$  (there are 200 possible states)
  - as a matter of comparison, the “state” L0 in the UML-like state diagram actually contains  $5^1 \times 2^2 \times 2 = 40$  states...
- However, as we will see, *reachable* states are about 10 times less
- 2 initial states: turn may be initialized with any value in its domain
- Note that `01.2_peterson.no_rulesets.no_parametric.m` we have rules repeated 2 times in a nearly equal fashion
- This can be done in this very simple model, but in general descriptions must be *parametric*

- If we want to check Peterson with 3 processes, currently we would have to add rules in the description
  - very similar to the ones already present, only changing the index to 3
- Instead, it must be possible to only change the value of  $N$  from 2 to 3
- To write parametric descriptions in Murphi, rules are grouped with *rulesets*
  - an index will allow to describe the behavior of the generic process  $i$
  - see 02.2.peterson.with\_rulesets.no\_parametric.m, but invariant is still for two processes only

- Finally, in 03.2\_peterson.with\_rulesets.parametric.m also the invariant is parametric in  $N$ 
  - Exists  $x:T$   $E(x)$  End is equivalent to  $\vee_{x \in T} E(x)$
  - Forall  $x:T$   $E(x)$  End is equivalent to  $\wedge_{x \in T} E(x)$
  - all types  $T = \{x_1, \dots, x_{|T|}\}$  are finite, thus it is a finite formula